

L Number	Hits	Search Text	DB	Time stamp
1	140	348/92.ccls.	USPAT	2004/06/28 10:01
2	131	348/94.ccls.	USPAT	2004/06/28 10:01
3	5	(348/92.ccls. or 348/94.ccls.) and (substrat\$2 adj3 imag\$4)	USPAT	2004/06/28 10:11
4	11264	substrat\$2 adj3 imag\$4	USPAT	2004/06/28 10:12
5	1645	(substrat\$2 adj3 imag\$4) and (reciever or camera)	USPAT	2004/06/28 10:12
6	97	((substrat\$2 adj3 imag\$4) and (reciever or camera)) and (non	USPAT	2004/06/28 12:25
_		adj3 linear)		
7	10	348/92.ccls. and substrate	USPAT	2004/06/28 12:32
8	18	348/94.ccls. and substrate	USPAT	2004/06/28 12:34
9	119	348/86.ccls.	USPAT	2004/06/28 12:34
10 11	17 40854	348/86.ccls. and substrate substrat\$2 and interval	USPAT	2004/06/28 12:37
12	6752	(substrat\$2 and interval) and (light adj3 source)	USPAT USPAT	2004/06/28 12:38 2004/06/28 12:38
15	548	((substrat\$2 and interval) and (light adj3 source)) and (non	USPAT;	2004/06/28 13:32
		adj3 linear)	US-PGPUB;	2007/00/26 13.32
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
17	374	(((substrat\$2 and interval) and (light adj3 source)) and (non	USPAT;	2004/06/28 12:42
		adj3 linear)) and imag\$3	US-PGPUB;	. ,
			EPO; JPO;	
			DERWENT;	
1			IBM_TDB	
18	131	((((substrat\$2 and interval) and (light adj3 source)) and (non	USPAT;	2004/06/28 12:42
		adj3 linear)) and imag\$3) and camera	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
19	55	(((((substrat\$2 and interval) and (light adj3 source)) and (non	IBM_TDB USPAT;	2004/06/28 13:10
1 23		adj3 linear)) and imag\$3) and camera) and motor	US-PGPUB;	2004/00/20 13.10
		aujo micary) and maggo) and camera) and motor	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
23	139	356/237.3.ccls.	USPAT	2004/06/28 13:44
24	101	356/237.3.ccls. and defect\$3	USPAT	2004/06/28 13:11
25	46	(356/237.3.ccls. and defect\$3) and substrate	USPAT	2004/06/28 13:11
26	323	(((substrat\$2 and interval) and (light adj3 source)) and (non	USPAT;	2004/06/28 13:32
		adj3 linear)) and imag\$3 and position	US-PGPUB;	
			EPO; JPO; DERWENT;	
			IBM_TDB	
27	96	((((substrat\$2 and interval) and (light adj3 source)) and (non	USPAT;	2004/06/28 13:33
		adj3 linear)) and imag\$3 and position) and defect\$3	US-PGPUB;	200 1, 00, 20 15155
			EPO; JPO;	
			DERWENT;	
	_		IBM_TDB	
28	94	((((((substrat\$2 and interval) and (light adj3 source)) and (non	USPAT;	2004/06/28 13:43
		adj3 linear)) and imag\$3 and position) and defect\$3) and	US-PGPUB;	
		signal\$3	EPO; JPO;	
			DERWENT; IBM_TDB	
29	290734	detect\$4 and substrat\$3	USPAT;	2004/06/28 13:43
			US-PGPUB;	200 1/00/20 13.73
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
30	5842	(detect\$4 and substrat\$3) and ("non-linear" or (non adj2	USPAT	2004/06/28 13:45
		linear))		
31	431	((detect\$4 and substrat\$3) and ("non-linear" or (non adj2	USPAT	2004/06/28 13:46
32	396	linear))) and camera and (light same source)	LICOAT	2004/06/20 42:46
32	סצכ	(((detect\$4 and substrat\$3) and ("non-linear" or (non adj2 linear))) and camera and (light same source)) and substrate	USPAT	2004/06/28 13:46
<u> </u>		inical /// and camera and (light same source)) and substrate	<u></u>	L



33	374	((((detect\$4 and substrat\$3) and ("non-linear" or (non adj2	USPAT	2004/06/28 13:47
		linear))) and camera and (light same source)) and substrate)		
		and imag\$3		
34	368		USPAT	2004/06/28 13:48
		linear))) and camera and (light same source)) and substrate)		
		and imag\$3) and (interval or time)		
35	118	((((((detect\$4 and substrat\$3) and ("non-linear" or (non adj2	USPAT	2004/06/28 13:50
		linear))) and camera and (light same source)) and substrate)		
		and imag\$3) and (interval or time)) and motor		
36	113	(((((((detect\$4 and substrat\$3) and ("non-linear" or (non adj2	USPAT	2004/06/28 14:44
		linear))) and camera and (light same source)) and substrate)		
		and imag\$3) and (interval or time)) and motor) and optic\$3		
37	331	/	USPAT	2004/06/28 14:45
38	129	382/149.ccls. and substrate	USPAT	2004/06/28 14:46
39	9	(382/149.ccls. and substrate) and halogen	USPAT	2004/06/28 14:46